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**INTELLIGENT FRACTIONAL ORDER ITERATIVE LEARNING CONTROL USING
FEEDBACK LINEARIZATION FOR A SINGLE-LINK ROBOT**

Author(s)–Names, postal addresses and e-mail addresses of all authors:

IMAN GHASEMI

email: iman.ghasemi1367@gmail.com

ABOLFAZL RANJBAR NOEI

email: a.ranjbar@nit.ac.ir

JALIL SADATI

email: j.sadati@nit.ac.ir

Faculty of Electrical and Computer Engineering Department,
Babol University of Technology,
Babol,
Iran.

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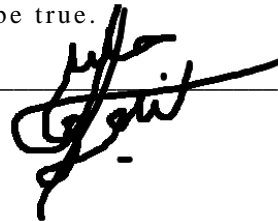
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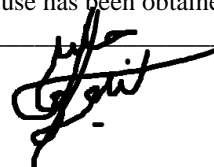
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