

EXISTENCE OF SOLUTIONS OF FRACTIONAL INTEGRODIFFERENTIAL SYSTEM WITH NONLOCAL CONDITIONS

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ABSTRACT: In the present paper we prove the existence and uniqueness of local solutions of a nonlocal Cauchy problem for a class of fractional integrodifferential equation. The results are obtained by using the theory of resolvent operators, the fractional powers of operators, fixed point techniques, and the Gelfand-Shilov principle.

ABSTRAK: Menerusi kertas kerja ini, kehadiran dan keunikan penyelesaian lokal terhadap permasalahan tak setempat Cauchy untuk peringkat pecahan persamaan integrodifferential dibuktikan. Keputusan diperolehi menggunakan teori operator leraian, operator kuasa pecahan, teknik titik tetap dan prinsip Gelfand-Shilov.

KEYWORDS: *fractional integrodifferential equation; nonlocal conditions; fractional powers; mild and classical solutions; resolvent operators*

1. INTRODUCTION

The purpose of this paper is to prove the existence and uniqueness of local solutions for nonlocal fractional integrodifferential equations of the form:

$$\frac{d^\alpha u(t)}{dt^\alpha} + A(t)u(t) = f(t, u(t)) + \int_0^t h\left(t, s, u(s), \int_0^s k(s, \tau, u(\tau))d\tau\right) ds, \quad (1.1)$$

$$u(0) + g(u) = u_0, \quad (1.2)$$

in a Banach space X , where $0 < \alpha \leq 1, t \geq 0$. Let $J = [0, T]$. We assume that $-A(t)$ is a closed linear operator defined on a dense domain $D(A)$ in X into X such that $D(A)$ is independent of t . It is considered also that $-A(t)$ generates an evolution operator in the Banach space X . Let $f: J \times X$ into $X, h: J \times J \times X \times X$ into $X, k: J \times J \times X$ into X and $g: C(J, X) \rightarrow D(A)$ be given nonlinear operators.

The differential equations involving fractional derivative in time have recently been proved to be valuable tools in the modeling of many phenomena in various fields of engineering, physics, economy and science. Indeed, we can find numerous applications in viscoelasticity, electrochemistry, porous media, electromagnetic etc. (see [1-6]). They involve a wide area of applications by bringing into a broader paradigm concepts of physics and mathematics [7-9]. Hence, fractional differential equations have become an object of extensive study during recent years as cited in [10-14] and references therein.

On the other hand, integrodifferential equations arise in many fields such as electronic, fluid dynamics, biological models and chemical kinetics. The equations of basic electric circuit analysis are well-known examples of these equations. Hence, the study of integrodifferential equation is very important. Fractional integrodifferential equations have been studied by many authors [8, 15-18]. Fractional integro-differential equations arise in many fields of engineering such as optimal control problem and heat conduction of materials with memory, etc. The nonlocal condition, which is a generalization of the classical initial condition, was motivated by physical problems. The problem of existence of solutions of evolution equation with nonlocal conditions in Banach space was first studied by Byszewski [19]. As indicated in [19, 20] and the references therein, the nonlocal condition $u(0) + g(u) = u_0$ can be applied in physics with better effect than the classical condition $u(0) = u_0$.

In the present paper we have generalized the results given by Pazy [21], Balachandran and Chandrasekaran [22] and Debbouche [23]. The rest of this paper is organized as follows: In section 2, we give preliminary results and in section 3, we prove the results of existence and uniqueness of local solutions for the equations (1.1) – (1.2).

2. PRELIMINARIES

In this section, we introduce some notations, definitions and results about fractional calculus and resolvent operators. Following Gelfand and Shilov [24], we define the fractional integral of order $\alpha > 0$ as

$$I_a^\alpha f(t) = \frac{1}{\Gamma(\alpha)} \int_a^t (t-s)^{\alpha-1} f(s) ds,$$

and also, the fractional derivative of the function f of order $0 < \alpha < 1$

$${}_a D_t^\alpha f(t) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dt} \int_a^t f(s) (t-s)^{-\alpha} ds,$$

where f is an abstract continuous function on the interval $[a, b]$ and $\Gamma(\alpha)$ is the Gamma function, see [25].

Definition 2.1: By a solution of (1.1) – (1.2), we mean a function u with values in X such that:

- (1) u is continuous function on J and $u(t) \in D(A)$,
- (2) $\frac{d^\alpha u}{dt^\alpha}$ exists and is continuous on $(0, T)$, $0 < \alpha < 1$, and u satisfies (1.1) on $(0, T)$ and the nonlocal condition (1.2).

Definition 2.2: (See [26]) A resolvent operator for problem (1.1) – (1.2) is a bounded operator-valued function $R(t, s) \in B(X)$, $0 \leq s \leq t \leq T$, having the following properties:

- (a) $R(t, s)$ is strongly continuous in s and t , $R(s, s) = I$, the identity operator on X , $0 \leq s \leq T$, and $\|R(t, s)\| \leq M e^{\beta(t-s)}$ for some constants M and β .
- (b) $R(t, s)E \subset E$, $R(t, s)$ is strongly continuous in s and t on E , and E is the Banach space formed from $D(A)$, the domain $-A(t)$, endowed with the graph norm.
- (c) For every $x \in X$, $R(t, s)x$ is continuously differentiable in $s \in J$ and

$$\frac{\partial R}{\partial s}(t, s)x = R(t, s)A(s)x.$$

(d) For every $x \in X$, and $s \in J$, $R(t, s)x$ is continuously differentiable in $t \in J$ and

$$\frac{\partial R}{\partial t}(t, s)x = -A(t)R(t, s)x,$$

with $\frac{\partial R}{\partial s}(t, s)x$ and $\frac{\partial R}{\partial t}(t, s)x$ are strongly continuous on $0 \leq s \leq t \leq T$. Here, $R(t, s)$ can be deduced from the evolution operator of the generator $-A(t)$. The resolvent operator is similar to the evolution operator for non-autonomous differential equations in Banach space. It will not, however, be an evolution operator because it will not satisfy an evolution or semigroup property. Because a number of results follow directly from the definition of resolvent operator.

Definition 2.3: A continuous solution $u: J \rightarrow X$ is said to be a mild solution of problem (1.1) – (1.2) on J if for all $u_0 \in X$, it satisfies the following integral equation

$$u(t) = R(t, 0)[u_0 - g(u)] + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} R(t, s) \left[f(s, u(s)) + \int_0^s h\left(s, \tau, u(\tau), \int_0^\tau k(\tau, \mu, u(\mu)) d\mu\right) d\tau \right] ds. \quad (2.1)$$

We define the fractional power $A^{-q}(t)$ by

$$A^{-q}(t) = \frac{1}{\Gamma(q)} \int_0^\infty x^{q-1} R(x, t) dx, \quad q > 0.$$

For $0 < q \leq 1$, $A^q(t)$ is a closed linear operator whose domain $D(A^q) \supset D(A)$ is dense in X . The closedness of A^q implies that $D(A^q)$, endowed with the graph norm of A^q , $\|u\|_{D(A^q)} = \|u\| + \|A^q u\|$, $u \in D(A^q)$, is a Banach space. Since $0 \in \rho(A)$, A^q is invertible. Its graph norm $\|\cdot\|$ is equivalent to the norm $\|u\|_q = \|A^q u\|$. Thus $D(A^q)$ equipped with the norm $\|\cdot\|_q$ is a Banach space, which we denote by X_q .

3. EXISTENCE THEOREM

To prove the main results we state the following lemma:

Lemma 3.1: (see [21, section 2.6]) Let $A(t)$ be the infinitesimal generator of a resolvent operator $R(t, s)$. We denote by $\rho[A(t)]$ the resolvent set of $A(t)$. If $0 \in \rho[A(t)]$, then

- (a) $R(t, s): X \rightarrow D(A^q)$ for every $0 \leq s \leq t \leq T$ and $q \geq 0$,
- (b) For every $u \in D(A^q)$, we have $R(t, s)A^q(t)u = A^q(t)R(t, s)u$,
- (c) The operator $A^q R(t, s)$ is bounded and $\|A^q R(t, s)\| \leq M_{q,\beta}(t-s)^{-q}$.

Theorem 1.1: Assume that

- (a) $-A(t)$ is the infinitesimal generator of a resolvent operator $R(t, s)$, $0 \leq s \leq t \leq T$, in X .
- (b) $0 \in \rho[-A(t)]$, the resolvent set.
- (c) For $q \geq 0$, the fractional power A^q satisfies $\|A^q R(t, s)\| \leq M_{q,\beta}(t-s)^{-q}$ for $0 \leq s \leq t \leq T$, where $M_{q,\beta}$ is a real constant.

- (d) For an open subset P of $J \times X_q$, $f: P \rightarrow X$ satisfies the condition, if for every $(t, u) \in P$ there is a neighborhood $V \subset P$ and constants $L \geq 0, 0 < \vartheta \leq 1$, such that

$$\|f(t_1, u_1) - f(t_2, u_2)\| \leq L(|t_1 - t_2|^\vartheta + \|u_1 - u_2\|_q) \quad (3.1)$$

for all $(t_i, u_i) \in V, i = 1, 2$.

- (e) For an open subset Q of $J \times J \times X_q \times X_q, h: Q \rightarrow X$ satisfies the condition, if for every $(t, s, u, v) \in Q$ there is a neighborhood $U \subset Q$ and constants $L_1 \geq 0, 0 < \vartheta \leq 1$, such that

$$\begin{aligned} & \|h(t_1, s_1, u_1, v_1) - h(t_2, s_2, u_2, v_2)\| \\ & \leq L_1(|t_1 - t_2|^\vartheta + |s_1 - s_2|^\vartheta + \|u_1 - u_2\|_q + \|v_1 - v_2\|_q) \end{aligned} \quad (3.2)$$

for all $(t_i, s_i, u_i, v_i) \in U, i = 1, 2$.

- (f) For an open subset R of $J \times J \times X_q, k: R \rightarrow X$ satisfies the condition, if for every $(t, s, u) \in R$ there is a neighborhood $W \subset R$ and constants $L_2 \geq 0, 0 < \vartheta \leq 1$, such that

$$\|k(t_1, s_1, u_1) - k(t_2, s_2, u_2)\| \leq L_2(|t_1 - t_2|^\vartheta + |s_1 - s_2|^\vartheta + \|u_1 - u_2\|_q) \quad (3.3)$$

for all $(t_i, s_i, u_i) \in W, i = 1, 2$.

- (g) $g: Y \rightarrow X_q$ is continuous and there exists a number b such that $\|R(t, 0)\| < \frac{1}{2b}$ and

$$\|g(x) - g(y)\|_q \leq b\|x - y\|_\infty \quad (3.4)$$

for all $x, y \in Y$. Note that if $z \in Y$, then $A^{-q}z \in Y$.

Then the problem (1.1) – (1.2) has a unique local solution $u \in C([0, T]: X) \cap C^1((0, T): X)$.

Proof: Choose $t^* > 0$ and $\delta > 0$ such that estimates (3.1) – (3.4) hold on the sets

$$V = \{(t, u): 0 \leq t \leq t^*, \|u - u_0\| \leq \delta\},$$

$$U = \{(t, s, u, v): 0 \leq t, s \leq t^*, \|u - u_0\| \leq \delta, \|v - v_0\| \leq \delta\},$$

and $W = \{(t, s, u): 0 \leq t, s \leq t^*, \|u - u_0\| \leq \delta\}$, respectively.

Let $B = \max_{0 \leq t < T} \|f(t, u_0)\|$

and

$$H = \max_{0 \leq t, s \leq t^*} \left\| \left\| h \left(t, s, u_0, \int_0^s k(s, \tau, u_0) d\tau \right) \right\| \right\|$$

Set $\lambda = \sup_{x \in Y} \|g(x)\|_q$ and choose T such that for $0 \leq t < T$,

$$\|R(t, 0) - I\|[\|u_0\|_q + \lambda] \leq \frac{\delta}{2}, \quad 0 \leq t < T$$

and

$$0 < T < \min \left\{ t^*, \left[\frac{\delta}{2} M_{q, \beta}^{-1} \Gamma(\alpha) (\alpha - q) (L\delta + B + L_1 \delta T + L_1 L_2 \delta T^2 + HT)^{-1} \right]^{\frac{1}{\alpha - q}} \right\} \quad (3.5)$$

Let $Y = C((0, T]: X)$ be endowed with the supremum norm

$$\|y\|_\infty = \sup_{0 \leq t < T} \|y(t)\|_q, \quad y \in Y.$$

Then Y be a Banach space. Define a map $F: Y \rightarrow Y$

$$Fy(t) = R(t, 0)A^q[u_0 - g(A^{-q}y)] + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} A^q R(t, s) f(s, A^{-q}y(s)) ds + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} A^q R(t, s) \int_0^s h \left(s, \tau, A^{-q}y(\tau), \int_0^\tau k(\tau, \mu, A^{-q}y(\mu)) d\mu \right) d\tau ds. \quad (3.6)$$

Obviously, $Fy(0) = A^q[u_0 - g(A^{-q}y)]$. Let S be the nonempty closed and bounded subset of Y defined by

$$S = \{y: y \in Y, y(0) = A^q[u_0 - g(A^{-q}y)], \|y(t) - A^q[u_0 - g(A^{-q}y)]\| \leq \delta\}.$$

For $y \in S$, we have

$$\begin{aligned} \|Fy(t) - A^q[u_0 - g(A^{-q}y)]\| &\leq \|R(t, 0) - I\| \|A^q[u_0 - g(A^{-q}y)]\| \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|A^q R(t, s)\| \|f(s, A^{-q}y(s)) - f(s, u_0)\| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|A^q R(t, s)\| \|f(s, u_0)\| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|A^q R(t, s)\| \left\| \int_0^s h \left(s, \tau, A^{-q}y(\tau), \int_0^\tau k(\tau, \mu, A^{-q}y(\mu)) d\mu \right) d\tau \right. \\ &\quad \left. - \int_0^s h \left(s, \tau, u_0, \int_0^\tau k(\tau, \mu, u_0) d\mu \right) d\tau \right\| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|A^q R(t, s)\| \left\| \int_0^s h \left(s, \tau, u_0, \int_0^\tau k(\tau, \mu, u_0) d\mu \right) d\tau \right\| ds \\ &\leq \frac{\delta}{2} + \frac{M_{q,\beta}}{\Gamma(\alpha)} (\alpha - q)^{-1} T^{\alpha-q} (L\delta + B) + \frac{M_{q,\beta}}{\Gamma(\alpha)} (\alpha - q)^{-1} T^{\alpha-q} \{L_1(\delta + L_2\delta T)T\} \\ &\quad + \frac{M_{q,\beta}}{\Gamma(\alpha)} (\alpha - q)^{-1} T^{\alpha-q} HT \\ &\leq \frac{\delta}{2} + \frac{M_{q,\beta}}{\Gamma(\alpha)} (\alpha - q)^{-1} T^{\alpha-q} [L\delta + B + L_1\delta T + L_1L_2\delta T^2 + HT] \leq \frac{\delta}{2} + \frac{\delta}{2} = \delta. \end{aligned}$$

Therefore, F maps S into itself. Moreover, if $y_1, y_2 \in S$, then

$$\begin{aligned} \|Fy_1(t) - Fy_2(t)\| &\leq \|R(t, 0)\| \|g(A^{-q}y_1) - g(A^{-q}y_2)\|_q \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|A^q R(t, s)\| \|f(s, A^{-q}y_1(s)) - f(s, A^{-q}y_2(s))\| ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} \|A^q R(t, s)\| \left\| \int_0^s h \left(s, \tau, A^{-q}y_1(\tau), \int_0^\tau k(\tau, \mu, A^{-q}y_1(\mu)) d\mu \right) \right. \\ &\quad \left. - \int_0^s h \left(s, \tau, A^{-q}y_2(\tau), \int_0^\tau k(\tau, \mu, A^{-q}y_2(\mu)) d\mu \right) d\tau \right\| ds \end{aligned}$$

$$\begin{aligned} &\leq b\|R(t, 0)\| \|y_1 - y_2\|_\infty + \frac{1}{\Gamma(\alpha)} M_{q,\beta} T^{\alpha-q} (\alpha - q)^{-1} L \|y_1 - y_2\|_Y \\ &\quad + \frac{1}{\Gamma(\alpha)} M_{q,\beta} T^{\alpha-q} (\alpha - q)^{-1} L_1 [(\|y_1 - y_2\|_Y + L_2 \|y_1 - y_2\|_Y T) T] \\ &\leq b\|R(t, 0)\| \|y_1 - y_2\|_Y + \frac{1}{\Gamma(\alpha)} M_{q,\beta} T^{\alpha-q} (\alpha - q)^{-1} [L + L_1(1 + L_2 T) T] \|y_1 - y_2\|_Y \\ &\leq \frac{1}{2} \|y_1 - y_2\|_Y + \frac{1}{2} \|y_1 - y_2\|_Y, \end{aligned}$$

which implies that $\|F y_1 - F y_2\| \leq \frac{1}{2} \|y_1 - y_2\|_Y + \frac{1}{2} \|y_1 - y_2\|_Y$.

By the contraction mapping theorem, mapping F has a unique fixed point $y \in S$. This fixed point satisfies the integral equation

$$\begin{aligned} y(t) &= R(t, 0) A^q [u_0 - g(A^{-q} y)] + \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} A^q R(t, s) f(s, A^{-q} y(s)) ds \\ &+ \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} A^q R(t, s) \int_0^s h \left(s, \tau, A^{-q} y(\tau), \int_0^\tau k(\tau, \mu, A^{-q} y(\mu)) d\mu \right) d\tau ds. \end{aligned} \tag{3.7}$$

From (3.1), (3.2) and the continuity of y it follow that

$$t \rightarrow f(t, A^{-q} y(t))$$

and

$$t \rightarrow h \left(t, s, A^{-q} y(s), \int_0^s k(s, \tau, A^{-q} y(\tau)) d\tau \right)$$

are continuous on $[0, T]$, and, hence, there exist constants N_1 and N_2 such that

$$\|f(t, A^{-q} y(t))\| \leq N_1 \tag{3.8}$$

and

$$\left\| h \left(t, s, A^{-q} y(s), \int_0^s k(s, \tau, A^{-q} y(\tau)) d\tau \right) \right\| \leq N_2 \tag{3.9}$$

By using the same method as in [20, Theorem 3.2], we can prove that $y(t)$ is locally Hölder continuous on $(0, T]$. Then there exist a constant C such that for every $t' > 0$, we have

$$\|y(t) - y(s)\| \leq C |t - s|^\nu,$$

for all $0 \leq t' \leq t, s \leq T$. The local Hölder continuity of $t \rightarrow f(t, A^{-q} y(t))$ follows from

$$\begin{aligned} \|f(t, A^{-q} y(t)) - f(s, A^{-q} y(s))\| &\leq L(|t - s|^\vartheta + \|y(t) - y(s)\|) \\ &\leq C_1(|t - s|^\vartheta + |t - s|^\nu) \end{aligned}$$

for some $C_1 > 0$ and the local Hölder continuity of

$$t \rightarrow h \left(t, s, A^{-q} y(s), \int_0^s k(s, \tau, A^{-q} y(\tau)) d\tau \right)$$

follows from

$$\left\| \left(h \left(t, s, A^{-q}y(s), \int_0^s k(s, \tau, A^{-q}y(\tau))d\tau \right) - h \left(t, \mu, A^{-q}y(\mu), \int_0^s k(\mu, \phi, A^{-q}y(\phi))d\phi \right) \right) \right\|$$

$$\leq L_1\{|s - \mu|^\vartheta + \|y(s) - y(\mu)\| + L_2(|s - \mu|^\vartheta + |\tau - \phi|^\vartheta + \|y(\tau) - y(\phi)\|)T\}$$

$$\leq L_1\{|s - \mu|^\vartheta + |s - \mu|^\gamma + L_3(|s - \mu|^\vartheta + |\tau - \phi|^\vartheta + |\tau - \phi|^\gamma)T\}$$

for some $L_3 > 0$. Let y be a solution of (3.7). Consider the inhomogeneous initial value problem

$$\frac{d^\alpha u(t)}{dt^\alpha} + A(t)u(t) = f(t, A^{-q}y(t)) + \int_0^t h \left(t, s, A^{-q}y(s), \int_0^s k(s, \tau, A^{-q}y(\tau))d\tau \right) ds \quad (3.10)$$

$$u(0) + g(A^{-q}y) = u_0 \quad (3.11)$$

This problem has a unique solution $u \in C^1((0, T]: X)$ [21], which is given by

$$u(t) = R(t, 0)[u_0 - g(A^{-q}y)] + \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} R(t, s) f(s, A^{-q}y(s)) ds$$

$$+ \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} R(t, s) \int_0^s h \left(s, \tau, A^{-q}y(\tau), \int_0^\tau k(\tau, \mu, A^{-q}y(\mu))d\mu \right) d\tau ds. \quad (3.12)$$

for $t > 0$, each term of (3.12) belongs to $D(A)$ and a *fortiori* in $D(A^q)$. Operating on both sides of (3.12) with A^q we find that

$$A^q u(t) = R(t, 0)A^q[u_0 - g(A^{-q}y)] + \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} A^q R(t, s) f(s, A^{-q}y(s)) ds$$

$$+ \frac{1}{\Gamma(\alpha)} \int_0^t (t - s)^{\alpha-1} A^q R(t, s) \int_0^s h \left(s, \tau, A^{-q}y(\tau), \int_0^\tau k(\tau, \mu, A^{-q}y(\mu))d\mu \right) d\tau ds. \quad (3.13)$$

From (3.7) the right hand side of (3.13) equals $y(t)$ and therefore $u(t) = A^{-q}y(t)$ and by (3.12), u is a $C^1((0, T]: X)$ solution of (1.1) – (1.2). The uniqueness of u follows from the uniqueness of the solutions of (3.7) and (3.10) – (3.11). Hence, the theorem is proved.

4. CONCLUSION

In this paper, the existence and uniqueness of mild and classical solutions for the nonlinear fractional integrodifferential equation with nonlocal condition are discussed. We applied the resolvent operators, the fractional powers of operators, fixed point technique and Gelfand-Shilov principle to establish the existence results. The results presented in this paper may be useful in the field of engineering and physics.

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